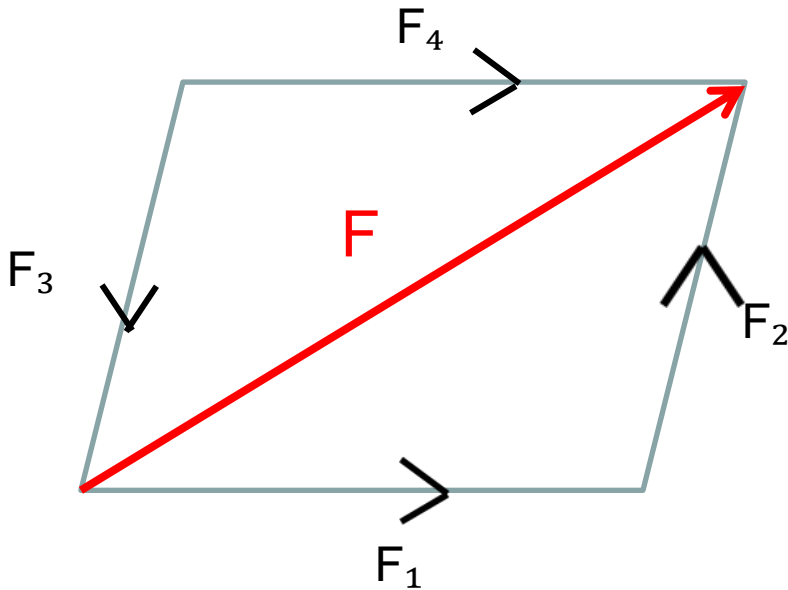
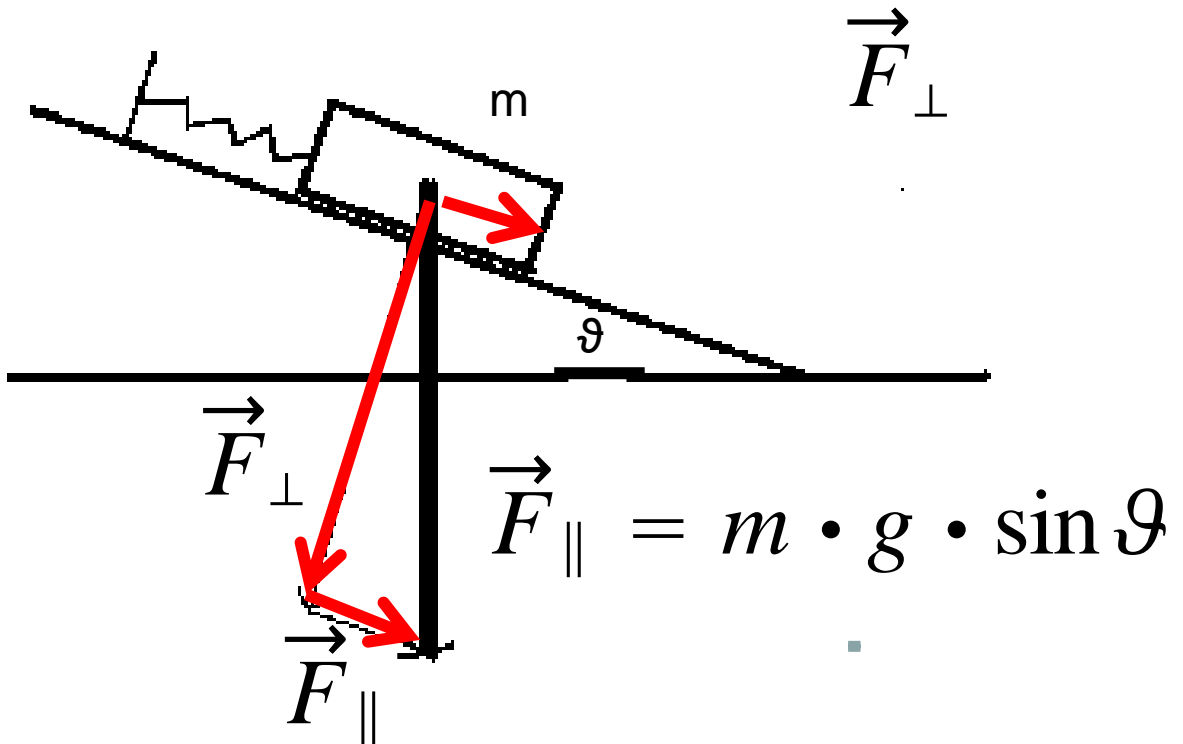


Decomposition of the force into components



Example: Inclined plane

Underlay compensates

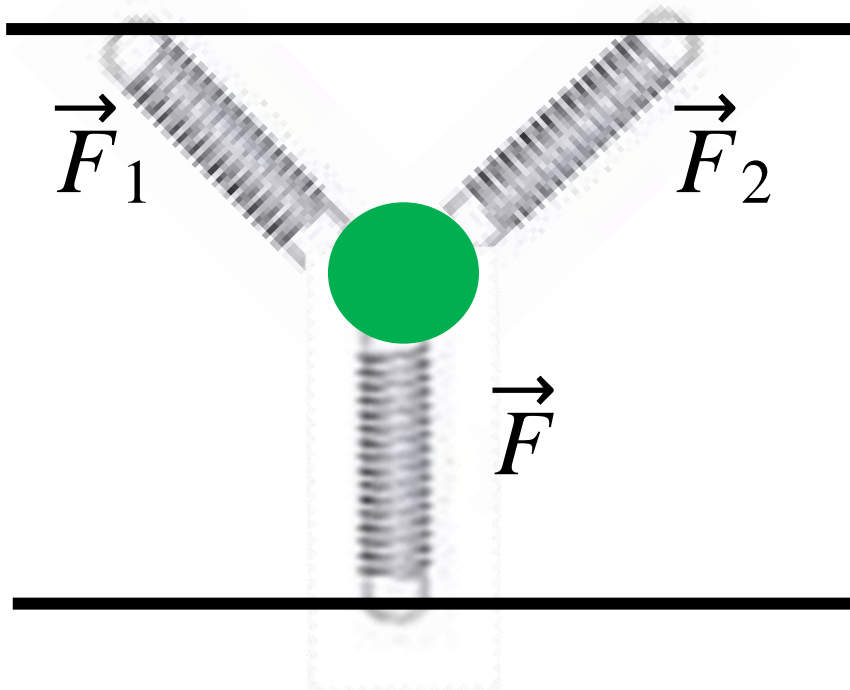


$$\vec{F}_{\perp} = m \cdot g \cdot \cos \vartheta$$

For several forces \vec{F}_i the resulting force

$$\vec{F} = \sum_{i=1}^N \vec{F}_i$$

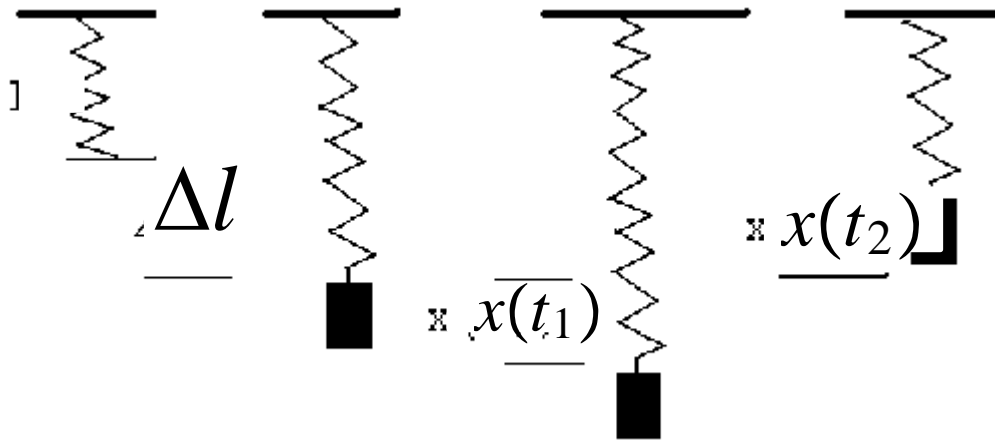
Special case $\vec{F} = \sum_{i=1}^N \vec{F}_i = 0$



Is called equilibrium

Force as origin of movement

Example: Elastic pendulum



Equilibrium: Δl Displacements: $x(t_1), x(t_2)$

Additional displacement results in a additional force \vec{F}

$$\vec{F} = -D \vec{x}; [F] = N(\text{Newton})$$

Using the second law of Newton:

$$m \cdot \vec{a} = -D \cdot \vec{x}$$

a: Resulting acceleration, m resistance against acceleration

$$m \cdot \ddot{x} = -D \cdot x$$

Linear differential equation

Look for $x = x(t)$

Result via Ansatz: $x = x_0 \cos \omega t$

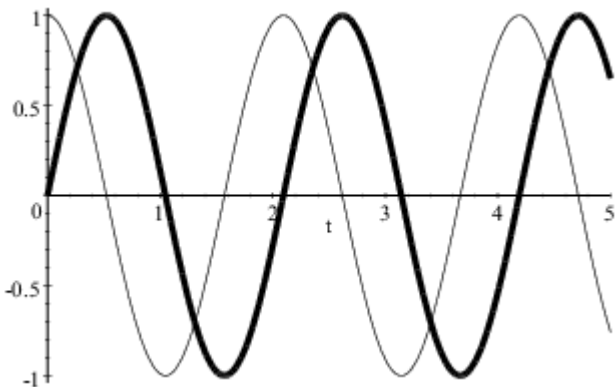
$$\omega = \text{constant}[\omega] = s^{-1}$$

$$\text{Derivation } t: \dot{x} = -\omega x_0 \sin \omega t$$

$$\ddot{x} = -\omega^2 x_0 \cos \omega t$$

$$\rightarrow -m \cdot \omega^2 \cdot x_0 \cdot \cos \omega t = -x_0 \cdot D \cdot \cos \omega t$$

$$\omega^2 = \frac{D}{m} \rightarrow \rightarrow \rightarrow \rightarrow \omega = \sqrt{\frac{D}{m}}$$



Oscillation

Frequency: ν

Period: $\omega = 2\pi \cdot \nu$

T: Time of the period

$$\omega = 2\pi\nu = \frac{2\pi}{T} = \frac{\text{angle of the full circle}}{\text{running time of the circumference}}$$

$$T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{m}{D}}$$

Consequence: Starting with the assumption of a linear force yields a harmonic oscillation.

T independent of the amplitude.

1.3 Work and Power

work = force • distance

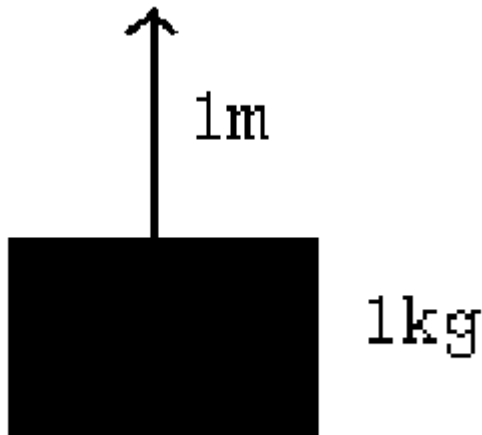
$$w = \vec{F} \cdot \vec{s}$$

Scalar (W) = Joule =

$$\mathbf{N \cdot m = W \cdot s}$$

Connection with
Electrodynamics:
Watt * second

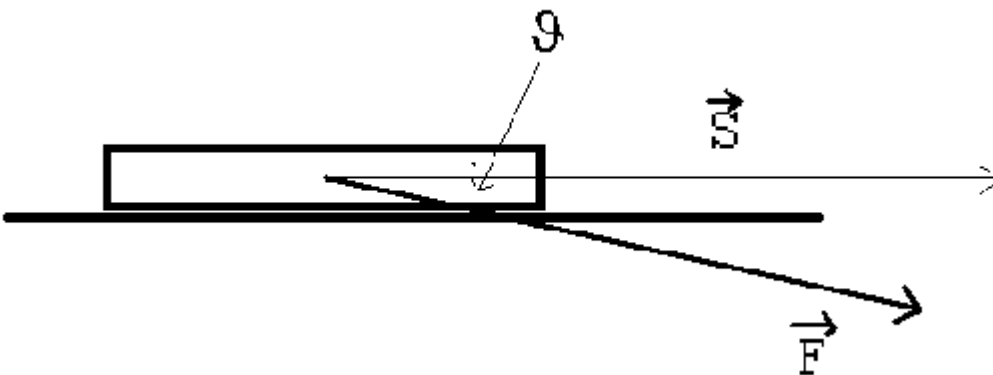
Work against gravity



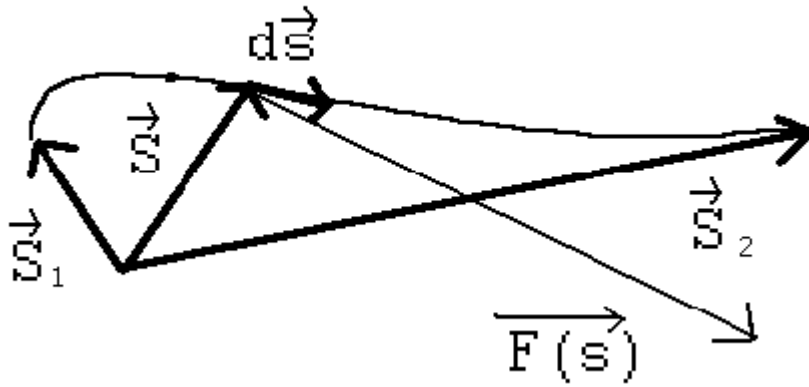
9.81 Joule
Ws
Nm

Compare:
2.35 cal
cal = 4.18Nm
Calorie:
Unit in Thermo-
dynamics

Scalar product of two vectors:



Here work
done on a
distance S



$$dW = \vec{F}(\vec{s})d\vec{s} \rightarrow W = \int_{S_1}^{S_2} \vec{F}(\vec{s})d\vec{s}$$

$$\text{Power } P = \frac{dW}{dt} = \dot{W}; [P] = J \cdot s^{-1} = Watt$$

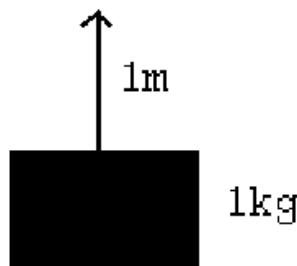
$$P = \frac{\vec{F}(t) \cdot d\vec{s}}{dt} = \vec{F}(t) \cdot \vec{v}(t)$$

1.4 Kinetic and potential energy

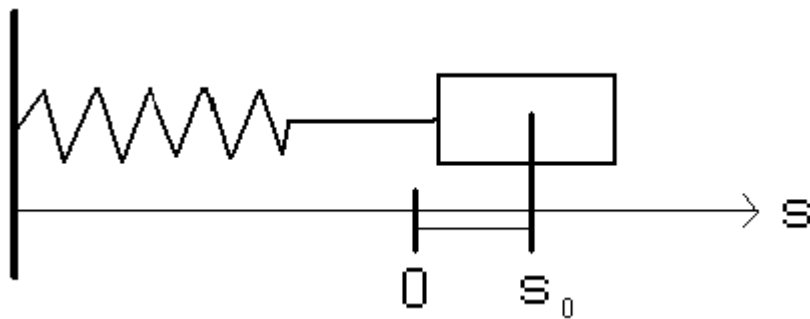
a) Potential Energy

Within the earth gravitational field: $m \cdot g \cdot h$

The work done remains as potential energy available: e.g.,:



Another example: Potential energy stored in a string

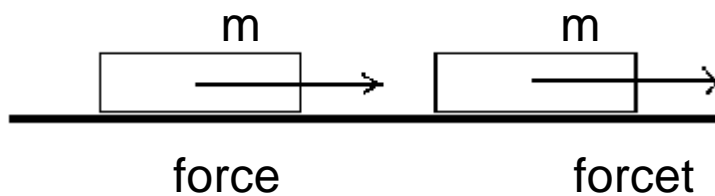


$$\leftarrow -D \cdot s_0$$

$$E_{pot} = \int_0^{s_0} D \cdot s \cdot ds = \frac{D \cdot s_0^2}{2}$$

b) Kinetic energy

Force: Reason of movement



t=0

s=0

v=0

t

s

v

Between $s=0$ and s :

$$\text{Work done: } W = F \cdot s$$

Energy must be due to movement of the body

;

$$F = a \cdot m = \frac{dv}{dt} \cdot m = m \cdot \frac{dv}{ds} \cdot \frac{ds}{dt} = m \cdot v \cdot \frac{dv}{ds}$$

$$F \cdot ds = m \cdot v \cdot dv$$

$$\int_0^s F \cdot ds = dW = \int_0^v m \cdot v' \cdot dv'$$

Constant force $\rightarrow F \cdot \int_0^s ds = m \cdot \int_0^v v' \cdot dv'$

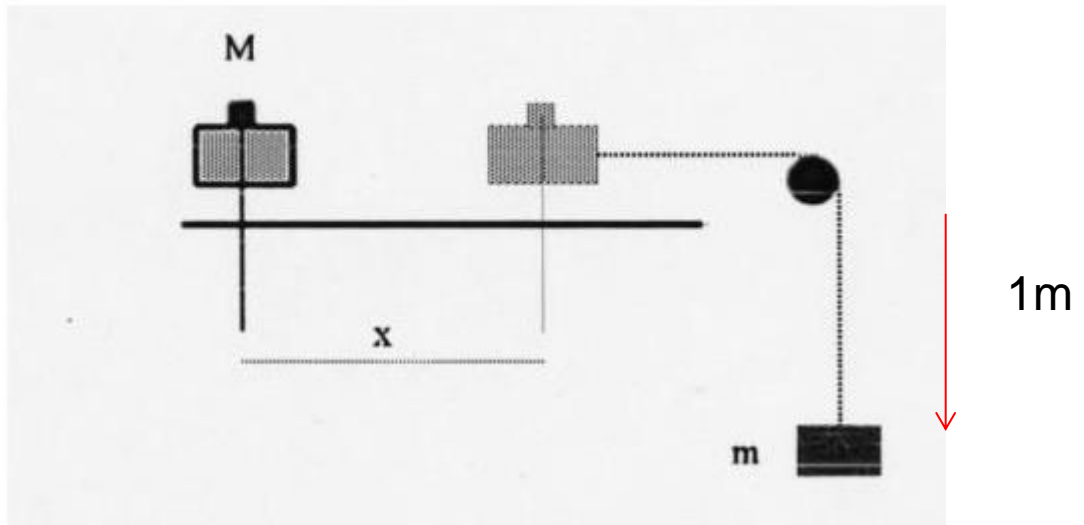
$$F \cdot s = \frac{m}{2} v^2$$

Work gets kinetic energy

$$E_{kin} = \frac{1}{2} m \cdot v^2$$

Experiment in a gravitational field

$$M=200\text{g}, m=10\text{g}$$



$x(m)$	Δt	v	v^2	$0.21 \cdot v^2$
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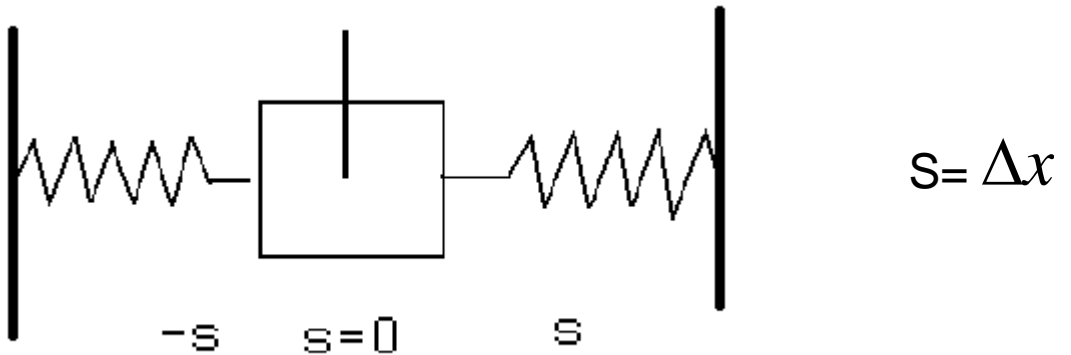
1	1.065	0.939	0.882	0.0926
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To compare with:

$$m \cdot g \cdot x = 0.01 \cdot 9.81 \cdot 1 = 0.0981 \text{ (Nm)}$$

Discrepancy: Friction

Experiment: Energy stored in a string :



$$E_{kin} = \frac{m}{2} \left(\frac{\Delta x}{\Delta t} \right)^2 \quad E_{pot} = \frac{1}{2} D \cdot s^2$$

Δt (s)	$\pm \Delta x$ (m)	m (kg)	E_{kin} Joule
0.277	0.01	0.205	0.013

Extracted from oscillation time

$$T = 2\pi \sqrt{\frac{m}{D}} = 1.7s \quad \longrightarrow$$

$$D = 2.8 kg \cdot s^{-2} \quad \text{and} \quad s = 0.01m$$

$$E_{pot} = 0.014J$$

Conclusion: Conservation of energy:

In a closed system :

$$E_{kin} + E_{pot} = \text{constant}$$

Power: s.above.

$$P = \frac{\vec{F}(t) \cdot d\vec{s}}{dt} = \vec{F}(t) \cdot \vec{v}(t)$$

Examples for magnitudes

Radiation of sun on top of earth's atmosphere: 1.367 kW/qm

Received on surface ca 1 kW/qm

Powerplant: 1 GW = 10^9 Watt

Car: e.g. : 50 kW

Plate on oven: 2 kW

Further examples:

Person: 80kg climbs in 10s on a staircase of 5m;

$$\begin{aligned}\implies P &= \frac{W}{t} = \vec{F} \cdot \vec{S} / t = m \cdot \vec{g} \cdot \vec{S} / t \\ &= \frac{80 \cdot 9.81 \cdot 5}{10} = 392.4 \text{ N} \cdot \text{m} / \text{s} = 0.53 \text{ PS}\end{aligned}$$

Mass m starting with constant power accelerating: (e.g.: E-loc.

$$\vec{F} \parallel \vec{v} \quad v?, a?$$

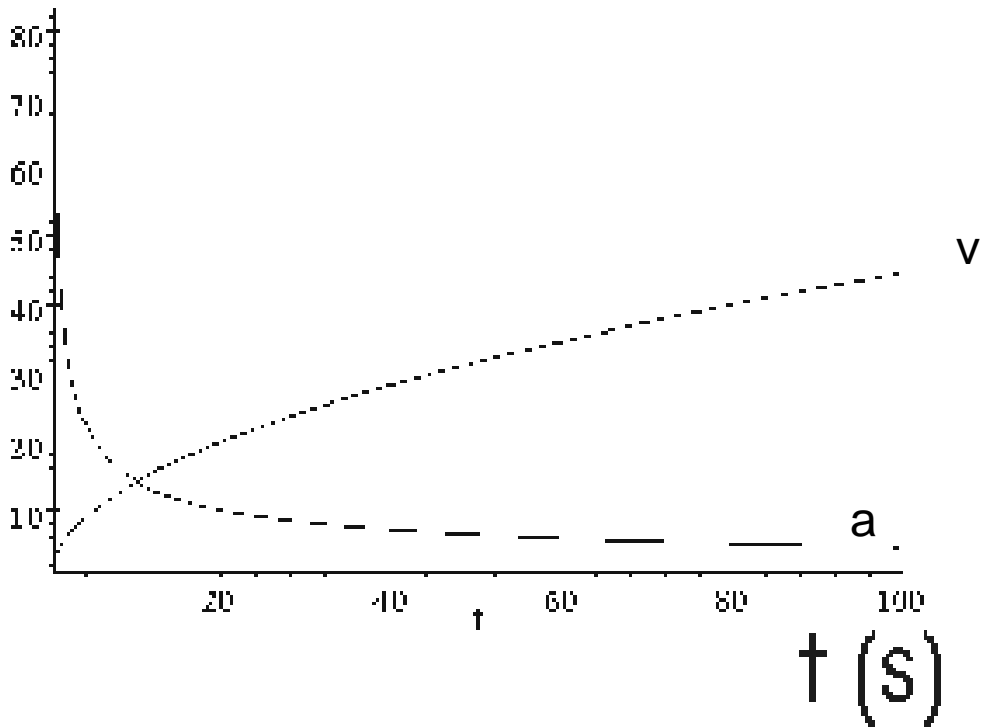
$$F = \frac{P}{v}; F = m \cdot a \implies \frac{P}{v} = m \cdot \frac{dv}{dt}$$

$$\implies v \cdot dv = \frac{P}{m} dt \implies$$

$$\int_0^{v(t)} v \cdot dv = \frac{P}{m} \cdot \int_0^t dt' \implies v^2(t) = \frac{2 \cdot P \cdot t}{m} \implies$$

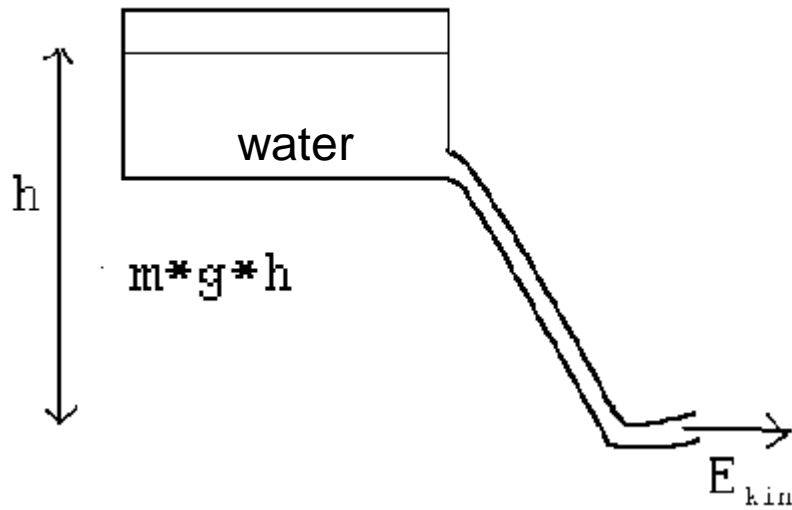
$$v(t) = \sqrt{\frac{2 \cdot P \cdot t}{m}} \quad a(t) = \sqrt{\frac{0.5 \cdot P}{m \cdot t}}$$

$a \cdot 10 (m/s^{**2}, v(m/s))$



Dam: Convert potential energy to kin. energy

$$v = \sqrt{2 \cdot g \cdot h}$$



Kaprun: $h=800m$

$v=125m/s=$
 $451km/h$

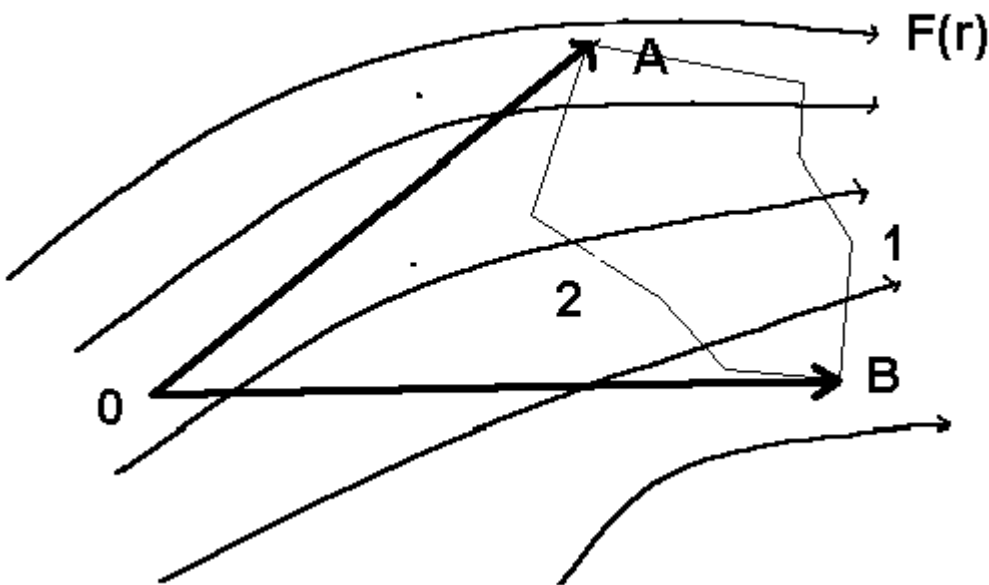
1.5 Field of forces, Potential

Field of forces: Region, a mass point feels a force

$$\vec{F} = \vec{F}(\vec{r})$$

Mass point transfer from A to B

$$\rightarrow \text{Work: } W(r_1, r_2) = \int_A^B \vec{F}(\vec{r}) d\vec{r}$$



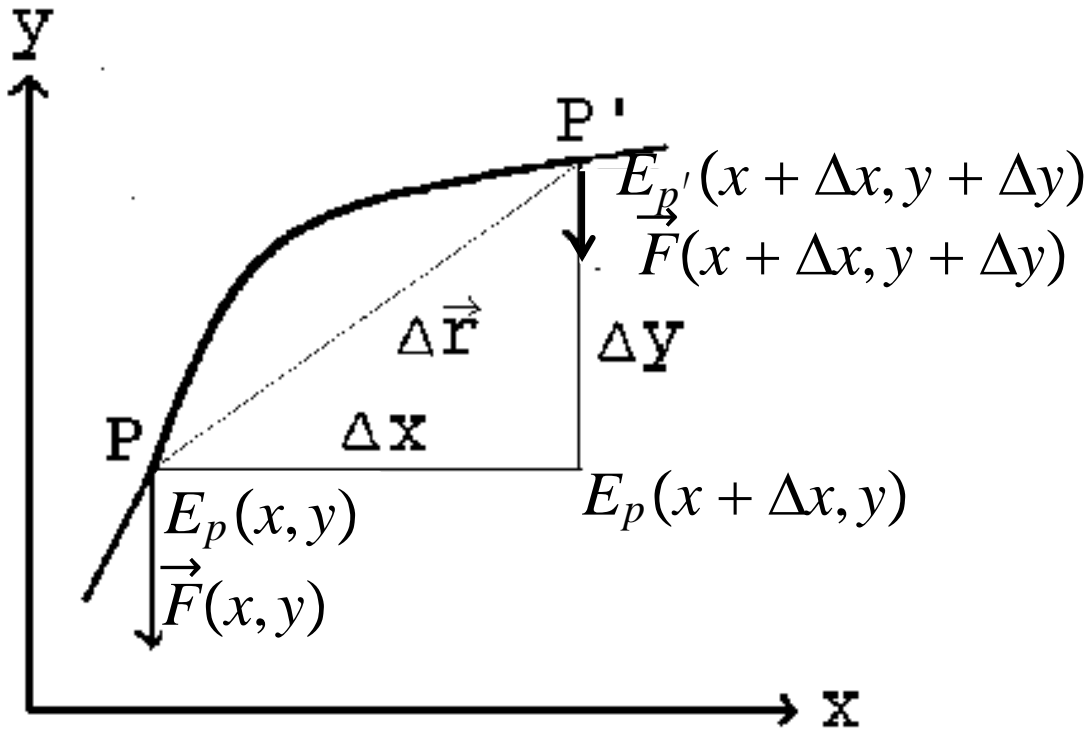
In many cases $W(r_1, r_2)$ independent of course

One speaks of conservative forces (fields).

$$\implies \int_A^B \vec{F}(\vec{r}) d\vec{r}_{\text{course1}} = \int_A^B \vec{F}(\vec{r}) d\vec{r}_{\text{course2}}$$

$$\oint \vec{F}(\vec{r}) d\vec{r} = 0$$

In a conservative force field:



E_p Potential energy

$$E_p(x, y) \rightarrow E_p(x + \Delta x, y + \Delta y)$$

$$E_p(x + \Delta x, y + \Delta y) - E_p(x, y) = \Delta E_p = \frac{\partial E_p}{\partial x} \Delta x +$$

$$P' \rightarrow P \quad \text{Change of potential energy} \quad \frac{\partial E_p}{\partial y} \Delta y$$

P' → → → P

$$\Delta W = \vec{F} \cdot \Delta \vec{r} = -\Delta E_p \rightarrow \rightarrow$$

$$F_x \cdot \Delta x + F_y \cdot \Delta y = -\frac{\partial E_p}{\partial x} \Delta x - \frac{\partial E_p}{\partial y} \Delta y$$

$$\rightarrow \rightarrow \rightarrow F_x = -\frac{\partial E_p}{\partial x}, F_y = -\frac{\partial E_p}{\partial y}$$

In general:

$$F = -\text{grad } E_p = -\nabla E_p$$

A look forward towards theoretical mechanics

$$m \ddot{x} - F(x, t) = 0$$

Newton

$$m \ddot{x} + \frac{\partial E_p}{\partial x} = 0$$

$$\frac{d}{dt} \frac{\partial}{\partial \dot{x}} \left(\frac{m \dot{x}^2}{2} \right) = \frac{d}{dt} \frac{\partial E_{kin}}{\partial \dot{x}}$$

$$\frac{d}{dt} \frac{\partial E_{kin}}{\partial \dot{x}} + \frac{\partial E_p}{\partial x} = 0$$

$$\text{mit } \frac{\partial L}{\partial \dot{x}} = \frac{\partial E_{kin}}{\partial \dot{x}} \text{ und } \frac{\partial L}{\partial x} = -\frac{\partial E_p}{\partial x}$$

Lagrange Function: $L(\dot{x}, x) = E_{kin}(\dot{x}) - E_p(x)$

The law of Newton can be written as:

$$\frac{d}{dt} \frac{\partial L(x, \dot{x})}{\partial \dot{x}} - \frac{\partial L(x, \dot{x})}{\partial x} = 0$$

Feynman II, 19

That is, how nature works!